

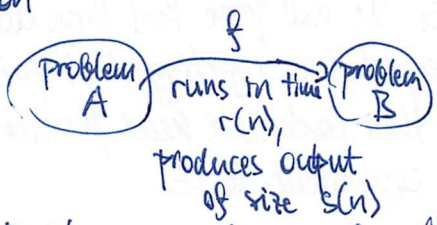
Exercise: Modify the proof to work for non-deterministic TMs.

FINE-GRAINED COMPLEXITY

Goal: Finer results than "polynomial vs. exponential"
 E.g., prove that a $\Theta(n^2)$ -time alg. is optimal.

Caveats: This will be model-dependent. We will assume RAM here.

Tool: Fine-grained reduction



If B can be solved in time $T(n)$, then A can be solved in time $O(r(n) + T(s(n)))$
 ↑ covers copying of input/output of f

Upper bounds for B imply upper bounds for A.
 Lower bounds for A imply lower bounds for B.

Orthogonal Vectors Problem (OV):

Input: two sets of vectors $A, B \subseteq \{0,1\}^d$, $|A|, |B| \leq n$

Question: are there $a \in A, b \in B$ s.t. $\langle a, b \rangle = 0$? ← i.e., bitwise AND is everywhere zero

Baseline algorithms: $O(n^2 d)$ trivial, $O(nd \cdot 2^d)$ ← for each $a \in A$, construct all orthogonal vectors and look them up in a suitable data structure for B (e.g., a trie)

Hypothesis (OVH): For no $\epsilon > 0$, there is an algorithm solving OV in time $O(n^{1-\epsilon} \cdot \text{poly}(d))$.

NFA Acceptance problem (NFAA):

Input: Non-deterministic finite-state automaton M of size $|M| = \#states + \#transitions$, string α .

Query: Does M accept α ?

Baseline: $O(|M| \cdot |\alpha|)$ by computing δ^* (see previous lecture)
 $O(2^{|M|} + |\alpha|)$ by reducing to a DFA first.

Theorem: Assuming OVH, there is no $\epsilon > 0$ s.t. NFAA can be solved in time $O((|M| \cdot |\alpha|)^{1-\epsilon})$.

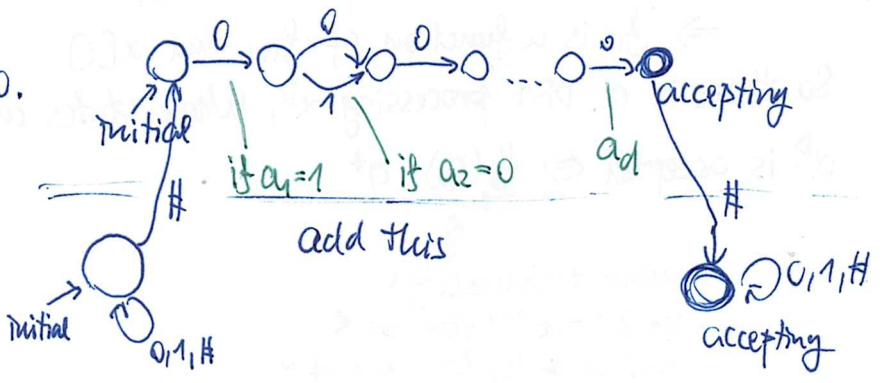
Proof: Will show reduction $OV \rightarrow$ NFAA running in time $O(nd)$, producing $|M| \in O(nd)$, $|\alpha| \in O(nd)$.

If NFAA can be solved in $O((|M| \cdot |\alpha|)^{1-\epsilon})$ time for some $\epsilon > 0$, then OV can be solved in $O((n^2 d)^{1-\epsilon}) = O(n^{2-2\epsilon} \cdot d^{2-2\epsilon})$ time, contradicting OVH.

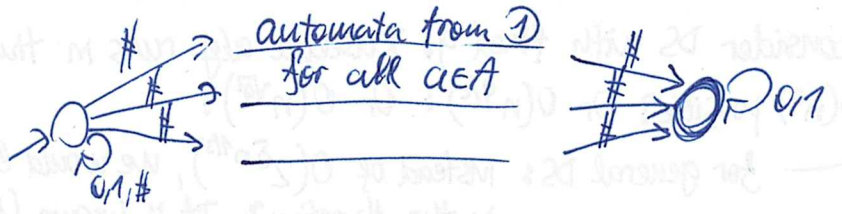
Now the reductions:

① given $a \in A$, construct NFA which accepts $b \Leftrightarrow \langle a, b \rangle = 0$.

② given a , construct NFA accepting $\#b^1\#b^2\#\dots\#b^n\# \Leftrightarrow \exists i: \langle a, b^i \rangle = 0$



③ Add a choice of $a \in A$:



Surprisingly, fine-grained bounds are connected with the "big world" of P vs. NP.

Exponential Time Hypothesis (ETH): ~~There~~ $\exists \epsilon > 0$ s.t. 3-SAT can't be solved in $O(2^{\epsilon N})$ time.

↳ justification: baseline alg. is $O(2^N \cdot \text{poly}(M, N))$ -time
 state-of-the-art alg. is $O(1.3280^N \cdot \text{poly}(M, N))$ -time.

for k-SAT:
 $N := \# \text{ variables,}$
 $M := \# \text{ clauses}$

Obviously, ETH implies $P \neq NP$.

improvements don't seem to converge towards 1

Strong ETH: $\forall \epsilon > 0 \exists k$ s.t. k-SAT cannot be solved in time $O(2^{\epsilon N})$.

(SETH) ↳ justification: state-of-the-art kSAT algs are slower for higher k, converging towards 2^N .

dependence on M is not important as $M \leq \binom{N}{k} \cdot 2^k$, which is polynomial for fixed k

It's known that SETH \Rightarrow ETH.

Dominating Set problem (DS)

Input: undirected graph with n vertices, $q > 0$

Question: is there a dominating set D of size q?

↳ for $G=(V, E)$: $D \subseteq V, \forall u \in V \exists v \in D: (u=v \text{ or } \{u, v\} \in E)$
 u dominated by v

Theorem: DS is NP-complete.

Proof: DS \in NP is trivial, will show NP-hardness by reducing 3-SAT to DS.



Will set $q=N$. This implies that a dom. set must use exactly 1 vertex from each var. gadget.

Formula satisfiable \Rightarrow choose dom. set according to assignment, check that all clause vertices are dominated.

Dom. set exists \Rightarrow choose assignment according to literals used in D ($d_i \in D \Rightarrow$ choose x_i arbitrarily), check that the formula is satisfied.

Theorem: ETH $\Rightarrow \exists \delta > 0$ s.t. DS cannot be solved in time $O(2^{\delta \cdot n^{1/3}})$.

Proof: Finer analysis of the same reduction.

Graph has n vertices, m edges for $n = 3N + M$
 $m \leq 3n$

we have $M \leq \binom{N}{3} \cdot 2^3 \leq 2N^3$,
 so $n \leq 3N^3$ for N large enough,
 $m \in O(n)$

Reduction runs in $O(n+m) = O(N^3)$ time.

If DS can be solved in $O(2^{\delta \cdot n^{1/3}})$ time, then 3SAT can in $O(2^{3^{1/3} \cdot \delta \cdot N})$.
 For δ small enough, this contradicts the ETH.

Now consider DS with fixed q . Baseline alg. runs in time $O\left(\binom{M}{q} \cdot qn\right) \leq O(n^{q+1})$. (50)
 Is $O(n^q)$ possible? Or $O(n^{q/2})$? Or $O(n^{\sqrt{q}})$?

for general DS: instead of $O(2^{\delta n^{1/3}})$, we would like $O(2^{\delta n})$... how to get rid of N^3 in the #vertices? It is known (but we won't prove it here) that 3-SAT is hard even for sparse formulas ($M \in O(N)$).

Theorem: If ETH holds, then $\exists \delta > 0 \forall^* q$: DS cannot be solved in $O(n^{\delta q})$ time.

Proof: We will show that a $O(n^{\delta q})$ -time alg. for DS with $q \geq \frac{2}{\delta}$ (*) implies a $O(2^{\delta N})$ alg. for 3-SAT. So for δ small enough, this would contradict the ETH.

Modify the previous reduction of 3-SAT to DS:

- ~~divide~~ ^{partition} variables to q groups per M/q variables
- variable gadgets: for each group, create vertices for all partial assignments setting variables in the group $\rightarrow 2^{M/q}$ vertices
 + add an extra d_i vertex
 edges form a clique
- clause gadgets: for each clause, add vertex c_i connected to all partial assignments which satisfy this clause

Again, a DS of size q selects a 1 vertex from each var. gadget.

This either selects one partial assignment to vars in the group or $d_i =$ "pick any".

Graph size: $n = q(2^{M/q} + 1) + M \in O(2^{M/q})$ for fixed q

$$m = (2^{M/q} + 1)^2 + 3M \in O(2^{2M/q}) \stackrel{\text{because of } *}{\leq} O(2^{\delta N})$$

Reduction takes $O(n+m) = O(2^{\delta N})$ time.

SAT is solved in $O(n^{\delta q}) \leq O(2^{\frac{N}{q} \cdot \delta q}) = O(2^{\delta N})$ time.

• For hardness of OV, we will need the SETH (plain ETH is not known to suffice)

Theorem: SETH \Rightarrow OVH.

Proof: Will show a reduction k -SAT \rightarrow OV will produce $n = 2^{M/2}$
 N variables \rightarrow $2n$ vectors $d = M$
 M clauses \rightarrow dimension d M time $O(nd)$, assuming k fixed.


So a $O(n^{2-\epsilon} d)$ alg. for OV implies a $O(2^{\frac{2-\epsilon}{2} N \cdot M})$ -time alg. for k -SAT, contradicting SETH for k large enough.

Reduction: Split variables to 2 groups X, Y of size $M/2$.

Construct A using X:

- vectors correspond to partial assignments to X $\left. \vphantom{\text{vectors}} \right\} 2^{M/2}$ vectors
- coordinates correspond to clauses $\left. \vphantom{\text{coordinates}} \right\} M$ coordinates
- "0" means that the clause is satisfied by the partial assgmt.

Similarly, construct B using Y.

 $\langle a, b \rangle = 0 \Leftrightarrow$ all clauses are satisfied by a ~~single~~ union of the two part. assgmts.

Problem: Longest Common Subsequence (LCS) — define $L(\alpha, \beta) :=$ ~~the~~ max. length of a common sub-sequence of α, β 51

Input: strings $\alpha, \beta \in \Sigma^*$, $|\alpha|, |\beta| \leq n$; $c > 0$

Output: Is $L(\alpha, \beta) > c$?

↑
Obtained by deleting elements while preserving order (i.e., not a subword)

Theorem: LCS can be solved in time $O(n^2)$ independent of $|\Sigma|$.

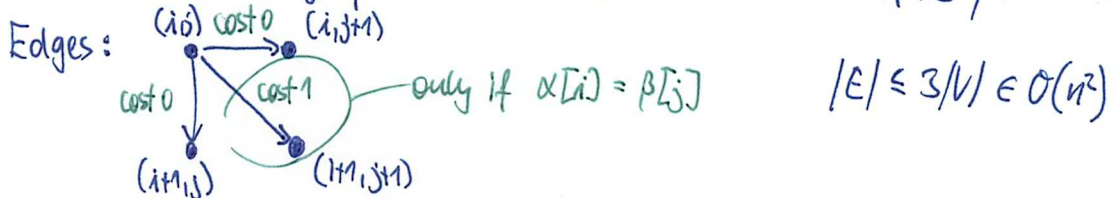
Proof: Let $A[i, j] := L(\alpha[:i], \beta[:j])$.

We have $A[0, j] = A[i, 0] = 0$,

$$A[i, j] = \min_{\text{for } i, j > 0} \begin{cases} A[i-1, j] \\ A[i, j-1] \\ A[i-1, j-1] + 1 \end{cases} \text{ only if } \alpha[i-1] = \beta[j-1]$$

Using this, we can fill in the table of $A[i, j]$'s row by row in time $O(n^2)$.
Then $A[n, n] = L(\alpha, \beta)$.

Alternative proof: Define a directed graph with $V = \{0\} \times \{0\} \cup \{0\} \times \{1\} \cup \{1\} \times \{0\} \cup \{1\} \times \{1\}$, $|V| \in O(n^2)$



Path from $(0,0)$ to $(|\alpha|, |\beta|)$ of cost c corresponds to a common subseq. of length c .

↳ LCS = cost of the longest path — but since the graph is acyclic, this can be computed using the same recurrence as in the previous proof. \Rightarrow the same $O(n^2)$ -time alg.

Theorem: Assuming ~~AVH~~ AVH, for no $\epsilon > 0$ there is a $O(n^{2-\epsilon})$ -time alg. for LCS.

Proof: Omitted, see the lecture notes by Karl Bringmann.

That's all, thanks for your attention! ☺