

Dependence of complexity on #tapes

Df: $L_{PAL} = \{ \alpha \alpha^R \mid \alpha \in \{0,1\}^* \}$ "even palindromes"
reversed

- trivial 2-tape TM deciding L_{PAL} in $\Theta(n)$ time.
- but all machines we found with 1 tape run in $\Theta(n^2)$ time!

Thm: Every 1-tape machine deciding L_{PAL} runs in time $\Omega(n^2)$.

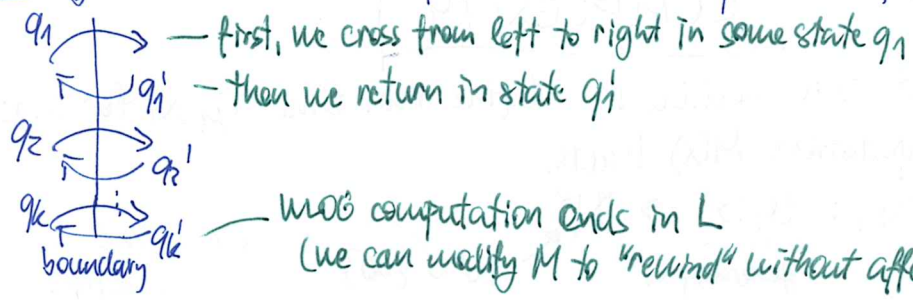
Proof: Assume there is M deciding L_{PAL} s.t. $T_M(n) \in o(n^2)$. \leftarrow that is: $\forall \epsilon > 0 \exists^\infty n : T_M(n) < \epsilon n^2$.

• Consider inputs of type:

part L	part Z	part R
α	$00 \dots 0$	α^R
$n/3$	$n/3$	$n/3$

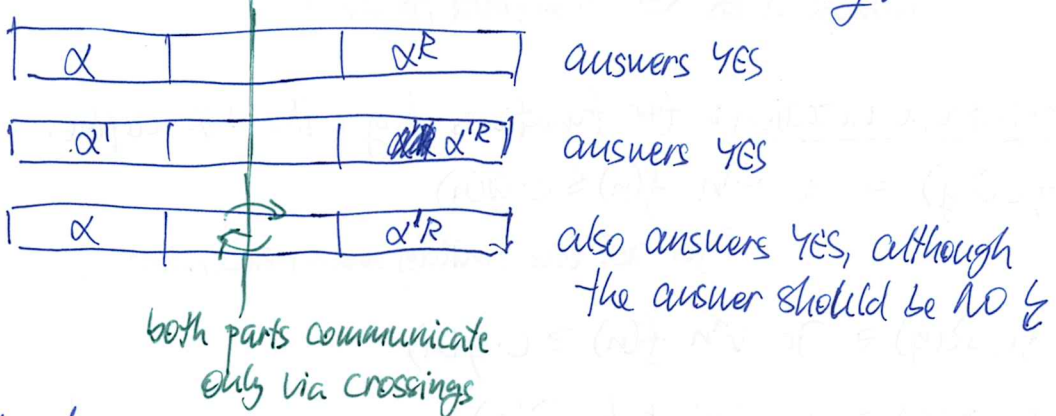
 \leftarrow answer is YES for every such string for $6/n$

• Consider boundary between 2 zeros in part Z & how computation of M crosses it:



\hookrightarrow crossing sequence $(q_1, q_1'), \dots, (q_k, q_k')$

• If two inputs with α, α' have the same C.S. for the same boundary:



• Similarly if they have same C.S. for different boundaries (part Z can have odd length, but that implies NO anyway)

• Let's use P.M.P. (Pigeon-hole principle) to show that such α, α' exist:

c.s. of length $k = |\Sigma|^{2k}$

c.s. of length at most $k \leq c \cdot |\Sigma|^{2k}$ for some constant c
(via sum of geom. series)

If #c.s. $<$ #inputs, then \exists two inputs with the same C.S.

\hookrightarrow so we want $c \cdot |\Sigma|^{2k} < 2^{n/3} \dots 2^{\log c + 2k \log |\Sigma|} < \frac{n}{2^3} \dots k < \frac{n}{9 \log |\Sigma|}$

- P. H. P. once again (we can find boundary with a small # crossings):
 - we have $n/3$ boundaries
 - \sum of lengths of their C.S. $\leq T_M(n) < \epsilon n^2$
 - $\Rightarrow \exists$ boundary with at most $\frac{\epsilon n^2}{n/3} = 3\epsilon n$ crossings

- now set ϵ such that we have:
 - min. # crossings $\leq 3\epsilon n < \frac{n}{9 \log |Q|}$ such ϵ exists & inequality satisfied for n large enough
- so there are 2 inputs with the same C.S. \Rightarrow mixing produces contradiction.

Thm: For every multi-tape TM M there is 1-tape TM M' s.t. $L(M) = L(M')$ & $T_{M'}(n) \in O(T_M(n)^2)$.

Proof: Analyze reduction from previous lectures. [hint: at most $T_M(n)$ tape cells used on each tape]

Thm: For every multi-tape TM M there is 2-tape TM M' s.t. $L(M) = L(M')$ & $T_{M'}(n) \in O(T_M(n) \cdot \log T_M(n))$.
(proof omitted)

Time complexity classes

• $DTIME(\underbrace{f}_{T_M \in O(f)}) := \{ L \in \{0,1\}^* \mid \exists M \text{ multi-tape TM deciding } L \text{ in time } O(f) \}$

$f: \mathbb{N} \rightarrow \mathbb{R}$ every finite Σ s.t. $|\Sigma| \geq 2$ would work this will be the default makes things easier, but for TMs it's not necessary because of time compression thm.

sometimes just $TIME(f)$
["D" is for "deterministic"]

- We will require f to have these properties:
 - ① non-decreasing
 - ② $\forall n f(n) \geq n$
 - ③ time-constructible $\equiv \exists$ TM M_f which for input 1^n produces output $1^{f(n)}$ in time $O(f(n))$
- "proper time complexity function"

• $P := \bigcup_{i \geq 1} DTIME(n^i)$ \leftarrow polynomial-time decidable languages

Why we like P :

Examples:

- reachability in graphs
- evaluation of Boolean formulas

- Corresponds (roughly) to "efficiently solvable"
- independent of model of computation (RAM gives the same P as TM)
- ~~functions~~ polynomials are the smallest set of functions containing constants & identity and closed under addition, multiplication and composition.

Classes of functions

- DTIME(f) := $\{g : \Sigma^* \rightarrow \Sigma^* \mid \exists \text{TM } M \text{ computing } g \text{ in time } O(f)\}$
- PF := $\bigcup_{i \geq 1} \text{DTIME}(n^i)$

👁 If $|f(n)| \in \text{poly}(n)$: $L_g := \{\langle x, i \rangle \mid i\text{-th bit of } g(x) \text{ is } 1\}$
 $L_g \in P \Leftrightarrow g \in \text{PF}$

$O(n^k)$ for some fixed k

encoded in binary

So studying only languages in P is WLOG.

Consider these problems:

as usually:
suitably encoded

path vs. walk ← can repeat
doesn't repeat vertices

1) HAMILTON PATH

Input: undirected graph G , vertices u, v
 Question: \exists path in G with endpoints u, v containing all vertices (exactly) once.

2) 3-COLORING

Input: undirected graph G
 $Q: \exists f: V(G) \rightarrow \{1, 2, 3\}$ s.t. $\forall \{u, v\} \in E(G): f(u) \neq f(v)$
 coloring of G with 3 colors

3) INDEPENDENT SET

Input: undirected graph $G, k \in \mathbb{N}$
 $Q: \exists A \subseteq V(G): |A| \geq k \ \& \ \forall u, v \in A: \{u, v\} \notin E(G)$

4) CLIQUE

Input: $G, k \in \mathbb{N}$
 $Q: \exists A \subseteq V(G): |A| \geq k \ \& \ \forall u, v \in A: \{u, v\} \in E(G)$

5) 0,1-Equations

Input: matrix A , vector b with 0/1 entries
 $Q: \exists x \in \{0, 1\}^n: Ax = b$ (evaluated in integers, not \mathbb{Z}_2)

6) SAT (Boolean satisfiability):

Input: Boolean formula $\varphi(x_1 \dots x_m)$ in CNF
 $Q: \exists x_1 \dots x_m \in \{0, 1\}$ s.t. $\varphi(\vec{x})$ is true.

For all these: we are looking for something we can easily recognize (poly-time), but we don't know how to find it in poly time.

Clause
 $\varphi \equiv (x_1 \vee x_2 \vee x_3) \wedge (\dots) \wedge (\dots)$

literals: either x_i or $\neg x_i$

(restriction to CNF is WLOG, see later)

(we cannot use thm. from Logic about equivalent formulas in CNF, because it blows up size exponentially)

Reductions will again prove themselves useful:

Def: For languages $K, L: K \stackrel{P}{\equiv} L \Leftrightarrow \exists f \in \text{PF}$ s.t.

$\forall x \in \Sigma^* \quad x \in K \Leftrightarrow f(x) \in L$
 polynomial-time many-to-one reduction

Properties of \leq_m^P :

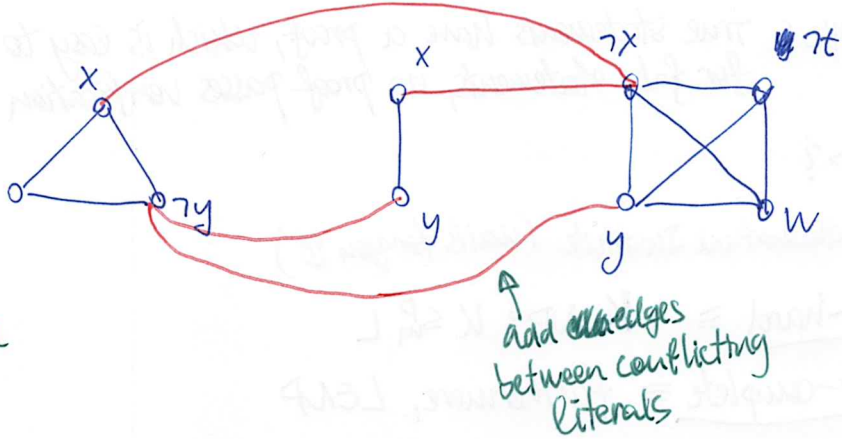
- reflexive & transitive (quasi-order)
- \exists incomparable languages (exercise)
- $K \leq_m^P L$ and $L \in P \Rightarrow K \in P$ [composition of 2 algorithms running in poly. time is again poly-time]

size of input for Alg2 is at most time complexity of Alg1

Example: SAT \leq_m^P INDEP SET

$$((x) \vee (\neg y) \vee (z)) \wedge (x \vee y) \wedge (\neg x \vee y \vee \neg z) \vee w$$

each clause gets complete subgraph labelled with literals of the clause



given a formula

produce a graph, $k := \# \text{clauses}$

from each subgraph we must select exactly 1 vertex

- \exists satisfying assignment: for each clause, pick 1 satisfied literal, put its vertex to the indep. set \rightarrow got 1 s.o. of size k
- \exists indep. set of size k: each vertex selected in i.s. selects a variable which will be set to 0/1 to satisfy the corresponding clause, red edges guarantee that we won't set var to both 0 and 1 - remaining variables set arbitrarily \rightarrow get satisfying assignment

the reduction runs in poly. time

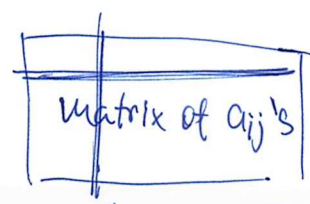
Example: INDEP SET \leq_m^P SAT ... given G, k , construct formula φ s.t. φ is satisfiable $\Leftrightarrow G$ has ind. set of size k

Variables: $x_1 \dots x_n$: vertex v_i selected to ind. set

a_{ij} for $1 \leq i \leq k, 1 \leq j \leq n$: vertex j is i -th in the ind. set \leftarrow order on vertices of the set

Clauses: $\forall \{v_i, v_j\} \in E(G): \neg x_i \vee \neg x_j$

$\forall i, j \ a_{ij} \Rightarrow x_j$ \leftarrow order describes the set (we allow unordered elements of set, which doesn't break anything)



$a_{ij} \Rightarrow \neg a_{ij}$ no number used multiple times

$a_{ij} \Rightarrow a_{ij}$ no vertex used twice or more

$a_{i1} \vee \dots \vee a_{in}$ each number used at least once

so we get CNF implication $x \Rightarrow y$ is a clause $\neg x \vee y$